#### **Bipartite Matching & the Hungarian Method**

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These notes follow formulation originally developed by Subhash Suri in *http://www.cs.ucsb.edu/~suri/cs230/Matching.pdf* 

We previously saw how to use the Ford-Fulkerson Max-Flow algorithm to find Maximum-Size matchings in bipartite graphs. In this section we discuss how to find Maximum-Weight matchings in bipartite graphs, a situation in which Max-Flow is no longer applicable.

The  $O(|V|^3)$  algorithm presented is the Hungarian Algorithm due to Kuhn & Munkres.

- Review of Max-Bipartite Matching Earlier seen in Max-Flow section
- Augmenting Paths
- Feasible Labelings and Equality Graphs
- The Hungarian Algorithm for Max-Weighted Bipartite Matching

#### **Application: Max Bipartite Matching**

A graph G = (V, E) is *bipartite* if there exists partition  $V = X \cup Y$  with  $X \cap Y = \emptyset$  and  $E \subseteq X \times Y$ .

A *Matching* is a subset  $M \subseteq E$  such that  $\forall v \in V$  at most one edge in M is incident upon v.

The size of a matching is |M|, the number of edges in M.

A *Maximum Matching* is matching M such that every other matching M' satisfies  $|M'| \leq M$ .

**Problem:** Given bipartite graph G, find a maximum matching.

### A bipartite graph with 2 matchings



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We now consider *Weighted* bipartite graphs. These are graphs in which each edge (i, j) has a weight, or value, w(i, j). The *weight* of matching M is the sum of the weights of edges in M,  $w(M) = \sum_{e \in M} w(e)$ .

**Problem:** Given bipartite weighted graph G, find a maximum weight matching.



Note that, without loss of generality, by adding edges of weight 0, we may assume that *G* is a complete weighted graph.

# **Alternating Paths:**



- Let M be a matching of G.
- Vertex v is matched if it is endpoint of edge in M; otherwise v is free
  Y<sub>2</sub>, Y<sub>3</sub>, Y<sub>4</sub>, Y<sub>6</sub>, X<sub>2</sub>, X<sub>4</sub>, X<sub>5</sub>, X<sub>6</sub> are matched, other vertices are free.
- A path is alternating if its edges alternate between M and E - M.
   Y<sub>1</sub>, X<sub>2</sub>, Y<sub>2</sub>, X<sub>4</sub>, Y<sub>4</sub>, X<sub>5</sub>, Y<sub>3</sub>, X<sub>3</sub> is alternating
- An alternating path is augmenting if both endpoints are free.
- Augmenting path has one less edge in M than in E M; replacing the M edges by the E M ones increments size of the matching.



An alternating tree is a tree rooted at some free vertex v in which every path is an alternating path.

Note: The diagram assumes a *complete* bipartite graph; matching M is the red edges. Root is  $Y_5$ .

# The Assignment Problem:

Let G be a (complete) weighted bipartite graph.

The Assignment problem is to find a max-weight matching in G.

A *Perfect Matching* is an M in which every vertex is adjacent to some edge in M.

A max-weight matching is perfect.

Max-Flow reduction dosn't work in presence of weights. The algorithm we will see is called the Hungarian Algorithm. Feasible Labelings & Equality Graphs





- A vetex *labeling* is a function  $\ell: V \to \mathcal{R}$
- A feasible labeling is one such that

 $\ell(x) + \ell(y) \ge w(x, y), \quad \forall x \in X, y \in Y$ 

• the *Equality Graph* (with respect to  $\ell$ ) is  $G = (V, E_{\ell})$  where

 $E_{\ell} = \{ (x, y) : \ell(x) + \ell(y) = w(x, y) \}$ 



**Theorem:** If  $\ell$  is feasible and M is a Perfect matching in  $E_{\ell}$  then M is a max-weight matching.

#### **Proof:**

Denote edge  $e \in E$  by  $e = (e_x, e_y)$ .

Let M' be any PM in G (not necessarily in in  $E_{\ell}$ ). Since every  $v \in V$  is covered *exactly* once by M we have

 $w(M') = \sum_{e \in M'} w(e) \le \sum_{e \in M'} (\ell(e_x) + \ell(e_y)) = \sum_{v \in V} \ell(v)$ 

so  $\sum_{v \in V} \ell(v)$  is an upper-bound on the cost of any perfect matching.

Now let M be a PM in  $E_{\ell}$ . Then  $w(M) = \sum_{e \in M} w(e) = \sum_{v \in V} \ell(v).$ 

So  $w(M') \leq w(M)$  and M is optimal.



**Theorem[Kuhn-Munkres]:** If  $\ell$  is feasible and M is a Perfect matching in  $E_{\ell}$  then M is a max-weight matching.

The KM theorem transforms the problem from an op*timization* problem of finding a max-weight matching into a combinatorial one of finding a perfect matching. It combinatorializes the weights. This is a classic technique in combinatorial optimization.

Notice that the proof of the KM theorem says that for any matching M and any feasible labeling  $\ell$  we have

$$w(M) \leq \sum_{v \in V} \ell(v).$$

This has very strong echos of the max-flow min-cut theorem.

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Our algorithm will be to

Start with any feasible labeling  $\ell$ and some matching  $M \subseteq E_{\ell}$ maintaining an alternating tree  $\mathcal{T} \subseteq E_{\ell}$ .

While M is not perfect repeat the following:

1. Find an augmenting path for M in  $E_{\ell}$ ; this increases size of MReset T to be one free vertex

2. If no augmenting path exists, improve ℓ to ℓ' such that M, T ⊂ E<sub>ℓ'</sub>. Add one edge in E<sub>ℓ'</sub> to T, keeping it an augmenting tree Go to 1.

Note that in each step of the loop we will either be increasing the size of M or T so this process must terminate.

Furthermore, when the process terminates, M will be a perfect matching in  $E_{\ell}$  for some feasible labeling  $\ell$ . So, by the Kuhn-Munkres theorem, M will be a maxweight matching.

# Finding an Initial Feasible Labelling



Finding an initial feasible labeling is simple. Just use:

 $\forall y \in Y, \, \ell(y) = 0, \qquad \forall x \in X, \, \ell(x) = \max_{y \in Y} \{w(x, y)\}$ 

With this labelling it is obvious that

 $\forall x \in X, y \in Y, w(x, y) \le \ell(x) + \ell(y)$ 

## Improving Labellings

Let  $\ell$  be a feasible labeling. Define *neighbor* of  $u \in V$  and set  $S \subseteq V$  to be

 $N_{\ell}(u) = \{ v : (u, v) \in E_{\ell}, \}, \quad N_{\ell}(S) = \bigcup_{u \in S} N_{\ell}(u)$ 

**Lemma:** Let  $S \subseteq X$  and  $T = N_{\ell}(S) \neq Y$ . Set

$$\alpha_{\ell} = \min_{x \in S, y \notin T} \{\ell(x) + \ell(y) - w(x, y)\}$$

and

$$\ell'(v) = \begin{cases} \ell(v) - \alpha_{\ell} & \text{if } v \in S \\ \ell(v) + \alpha_{\ell} & \text{if } v \in T \\ \ell(v) & \text{otherwise} \end{cases}$$

Then  $\ell'$  is a feasible labeling and, (i) If  $(x, y) \in E_{\ell}$  for  $x \in S, y \in T$  then  $(x, y) \in E_{\ell'}$ ; (ii) If  $(x, y) \in E_{\ell}$  for  $x \notin S, y \notin T$  then  $(x, y) \in E_{\ell'}$ ; (iii) For some  $x \in S, y \notin T$ we have  $(x, y) \notin E_{\ell}$  but  $(x, y) \in E_{\ell'}$ 

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#### **The Hungarian Method**

- 1. Generate initial labelling  $\ell$  and matching M in  $E_{\ell}$ .
- 2. If *M* perfect, stop. Otherwise pick free vertex  $u \in X$ . Set  $S = \{u\}, T = \emptyset$ . Note:  $S \cup T$  will be vertices of alternating tree
- 3. If  $N_{\ell}(S) = T$ , update labels (forcing  $N_{\ell}(S) \neq T$ )

 $\alpha_{\ell} = \min_{s \in S, \ y \notin T} \left\{ \ell(x) + \ell(y) - w(x, y) \right\}$ 

$$\ell'(v) = \begin{cases} \ell(v) - \alpha_{\ell} & \text{if } v \in S \\ \ell(v) + \alpha_{\ell} & \text{if } v \in T \\ \ell(v) & \text{otherwise} \end{cases}$$

4. If  $N_{\ell}(S) \neq T$ , pick  $y \in N_{\ell}(S) - T$ .

- If *y* free, *u* → *y* is augmenting path.
  Augment *M* and go to 2.
- If y matched, say to z, extend alternating tree:  $S = S \cup \{z\}, T = T \cup \{y\}$ . Go to 3.



- Initial Graph, trivial labelling and associated Equality Graph
- Initial matching:  $(x_3, y_1)$ ,  $(x_2, y_2)$
- $S = \{x_1\}, T = \emptyset.$
- Since  $N_{\ell}(S) \neq T$ , do step 4. Choose  $y_2 \in N_{\ell}(S) - T$ .
- $y_2$  is matched so grow tree by adding  $(y_2, x_2)$ , i.e.,  $S = \{x_1, x_2\}, T = \{y_2\}.$
- At this point  $N_{\ell}(S) = T$ , so goto 3.







- $S = \{x_1, x_2\}, T = \{y_2\}$ and  $N_{\ell}(S) = T$
- Calculate  $\alpha_{\ell}$

$$\alpha_{\ell} = \min_{x \in S, y \notin T} \begin{cases} 6+0-1, & (x_1, y_1) \\ 6+0-0, & (x_1, y_3) \\ 8+0-0, & (x_2, y_1) \\ 8+0-6, & (x_2, y_3) \end{cases}$$
$$= 2$$

- Reduce labels of *S* by 2; Increase labels of *T* by 2.
- Now  $N_{\ell}(S) = \{y_2, y_3\} \neq \{y_2\} = T.$



- $S = \{x_1, x_2\}, N_{\ell}(S) = \{y_2, y_3\}, T = \{y_2\}$
- Choose  $y_3 \in N_{\ell}(S) T$  and add it to T.
- $y_3$  is **not** matched in M so we have just found an alternating path  $x_1, y_2, x_2, y_3$  with two free endpoints. We can therefore augment M to get a larger matching in the new equality graph. This matching is perfect, so it must be optimal.
- Note that matching  $(x_1, y_2)$ ,  $(x_2, y_3)$ ,  $(x_3, y_1)$ has cost 6 + 6 + 4 = 16 which is exactly the sum of the labels in our final feasible labelling.

## Correctness:

- We can always take the trivial ℓ and empty matching M = Ø to start algorithm.
- If N<sub>ℓ</sub>(S) = T, we saw that we could always update labels to create a new feasible matching ℓ'. The lemma on page 13 guarantees that all edges in S × T and S × T that were in E<sub>ℓ</sub> will be in E<sub>ℓ'</sub>. In particular, this guarantees (why?) that the current M remains in E<sub>ℓ'</sub> as does the alternating tree built so far.

Note: The lemma requires that  $T \neq Y$  but this is trivially correct since |T| = |S| - 1 so |T| < |Y|.

If N<sub>ℓ</sub>(S) ≠ T, we can, by definition, always augment alternating tree by choosing some x ∈ S and y ∉ T such that (x, y) ∈ E<sub>ℓ</sub>. Note that at some point y chosen must be free, in which case we augment M.

- So the algorithm always terminates.
- M is a perfect matching in  $E_{\ell}$  when the algorithm terminates

— it is optimal by Kuhn-Munkres theorem.

# Complexity

In each phase of algorithm, |M| increases by 1 so there are at most *V* phases. How much work needs to be done in each phase?

In implementation,  $\forall y \notin T$  keep track of  $slack_y = \min_{x \in S} \{\ell(x) + \ell(y) - w(x, y)\}$ 

- Initializing all slacks at beginning of phase takes O(|V|) time.
- In step 4 we must update all slacks when vertex moves from \$\overline{S}\$ to \$S\$.
  This takes \$O(|V|)\$ time; only \$|V|\$ vertices can be moved from \$\overline{S}\$ to \$S\$, giving \$O(|V|^2)\$ time per phase.
- In step 3, α<sub>ℓ</sub> = min<sub>y∉T</sub> slack<sub>y</sub> and can therefore be calculated in O(|V|) time from the slacks. This is done at most |V| times per phase (why?) so only takes O(|V|<sup>2</sup>) time per phase. After calculating α<sub>ℓ</sub> we must update all slacks. This can be done in O(|V|) time by setting

 $\forall y \notin T$ ,  $slack_y = slack_y - \alpha_\ell$ . Since this is only done O(|V|) times, total time per phase is  $O(|V|^2)$ . There are |V| phases and  $O(|V|^2)$  work per phase so the total running time is  $O(|V|^3)$ .